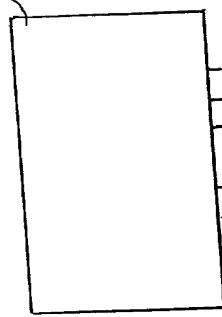


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200

100

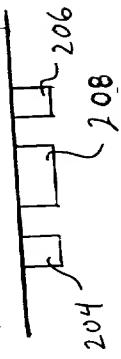
102



104

106

108

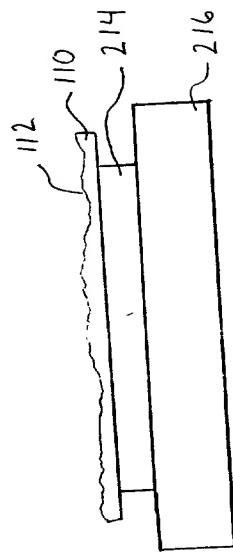


204

206

208

210



112

110

114

116

FIG. 2

FIG. 1

FIG. 3A

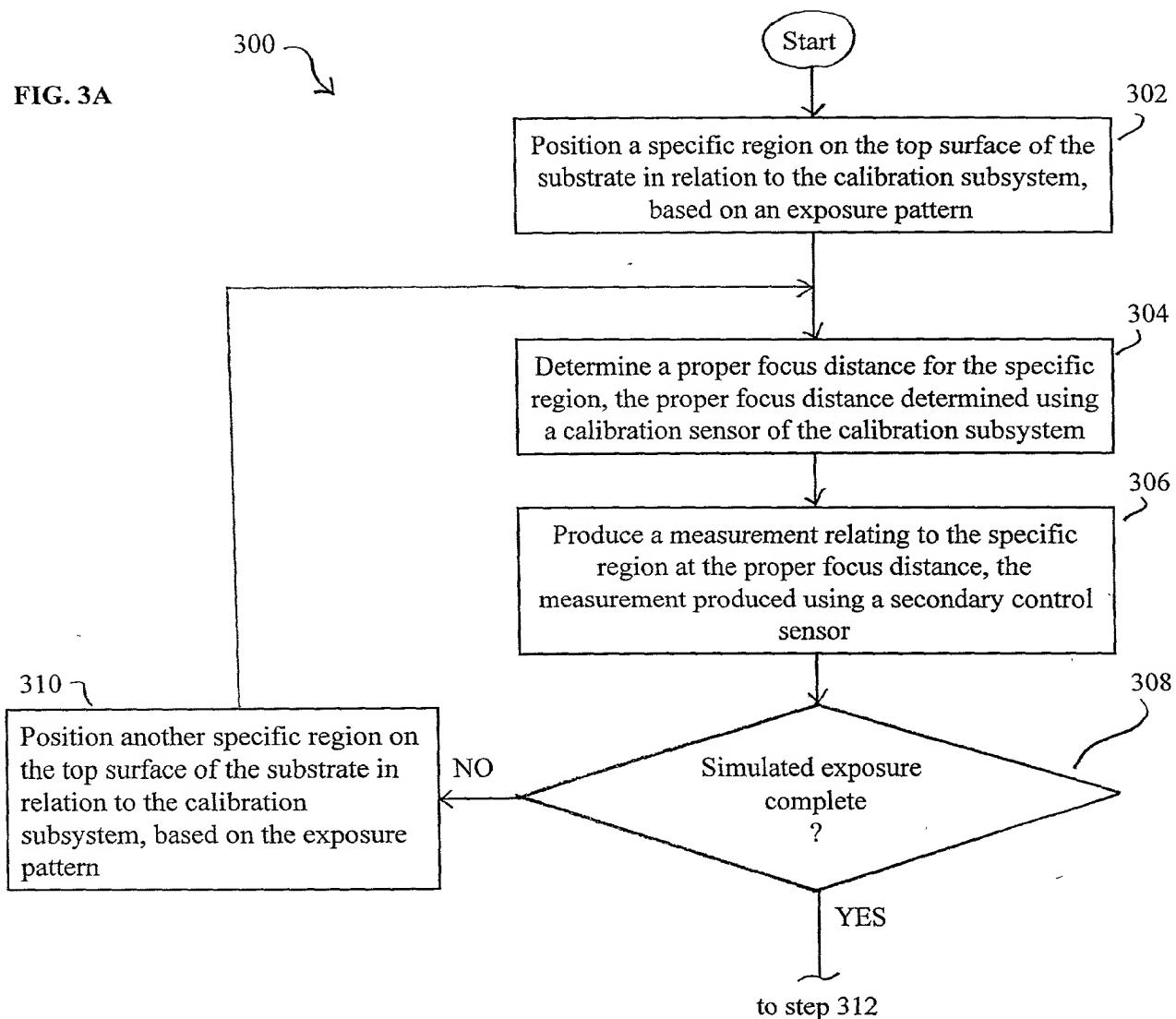
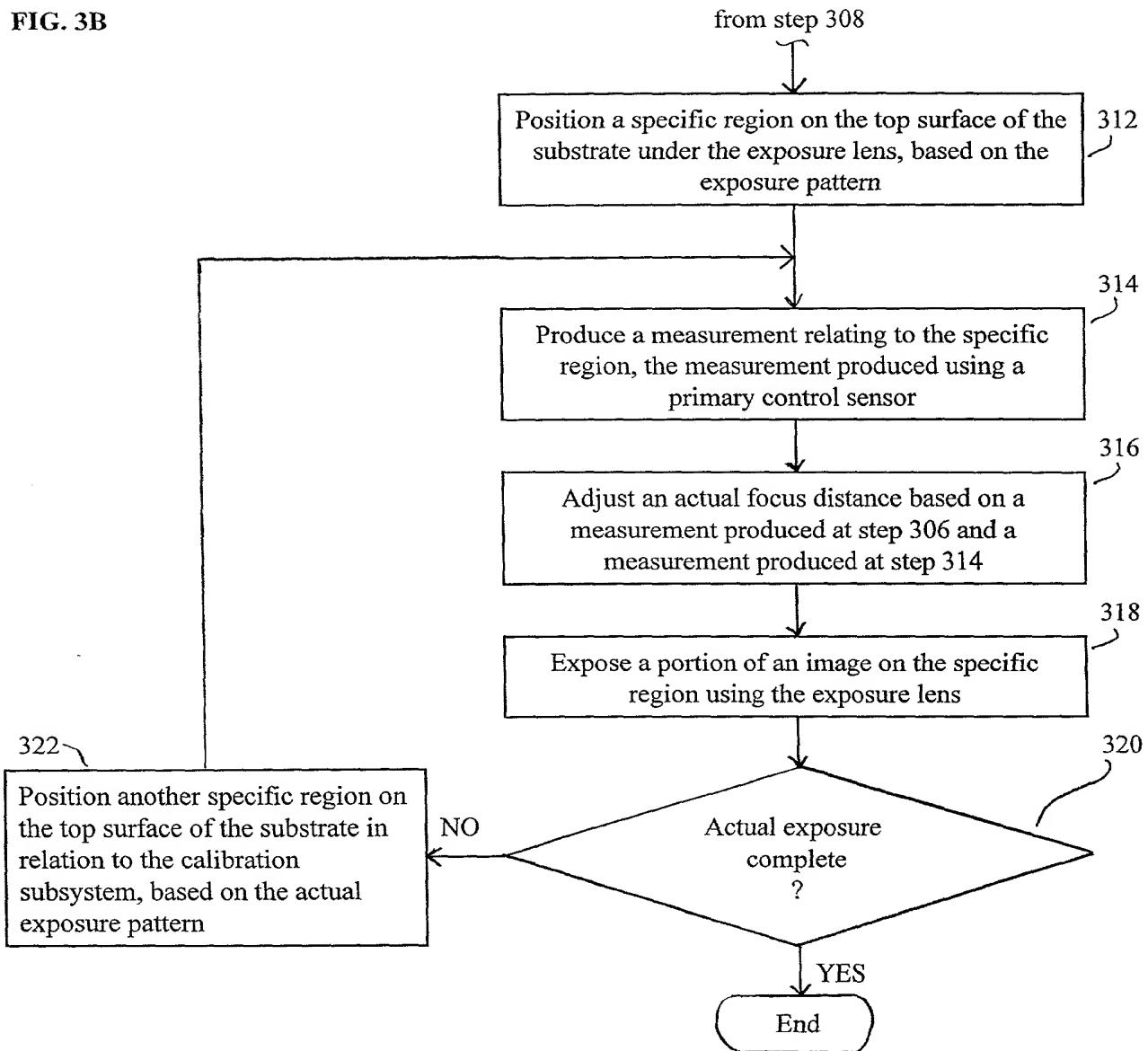


FIG. 3B



| X/Y Coordinates | Calibration Sensor Value (optional) | Control Sensor A Value | Control Sensor B Value | | Control Sensor N Value |
|-----------------|-------------------------------------|---|-------------------------|-------|-------------------------|
| X_1/Y_1 | Calibration _{1,1} | ControlA _{1,1} (i.e., x=y=1) | ControlB _{1,1} | | ControlN _{1,1} |
| X_1/Y_2 | Calibration _{1,2} | ControlA _{1,2} (i.e., x=1,y=2) | ControlB _{1,2} | | ControlN _{1,2} |
| X_1/Y_3 | Calibration _{1,3} | ControlA _{1,3} | ControlB _{1,3} | | ControlN _{1,3} |
| . | . | . | . | . | . |
| X_2/Y_1 | Calibration _{2,1} | ControlA _{2,1} | ControlB _{2,1} | | ControlN _{2,1} |
| X_2/Y_2 | Calibration _{2,2} | ControlA _{2,2} | ControlB _{2,2} | | ControlN _{2,2} |
| X_2/Y_3 | Calibration _{2,3} | ControlA _{2,3} | ControlB _{2,3} | | ControlN _{2,3} |
| . | . | . | . | . | . |
| X_3/Y_1 | Calibration _{3,1} | ControlA _{3,1} | ControlB _{3,1} | | ControlN _{3,1} |
| X_3/Y_2 | Calibration _{3,2} | ControlA _{3,2} | ControlB _{3,2} | | ControlN _{3,2} |
| X_3/Y_3 | Calibration _{3,3} | ControlA _{3,3} | ControlB _{3,3} | | ControlN _{3,3} |
| . | . | . | . | . | . |

FIG. 4